

Last Time: Curl and Divergence

$$\left. \begin{aligned} \text{curl}(\vec{v}) &= \nabla \times \vec{v} \\ &\quad \uparrow \\ &\quad \langle P, Q, R \rangle \end{aligned} \right\} \text{div}(\vec{v}) = \nabla \cdot \vec{v}$$

Prop: ①  $\text{curl}(\nabla f) = \vec{0}$

②  $\text{div}(\text{curl}(\vec{v})) = 0$

Interpretations of Curl and Divergence:

① Curl measures "how swirly is the v.f.?"

↳  $\text{curl}(\vec{v})$  is always "swirly".

② Divergence measures "does the v.f. tend to push points away from a little open region"?



↳ divergence  $\neq 0$



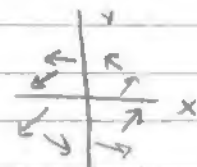
↳ swirly  
divergence = 0

Ex: Consider v.f.  $\langle P(x,y), Q(x,y), 0 \rangle = \vec{v}$

$$\text{curl}(\vec{v}) = \det \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & 0 \end{bmatrix}$$

$$= \langle -Q_z, +P_z, Q_x - P_y \rangle$$

$$= \langle 0, 0, Q_x - P_y \rangle = \langle 0, 0, \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \rangle$$



view from above

Recasting Green's Theorem w/ Vector Fields:

Let  $\vec{v} = \langle P(x,y), Q(x,y), 0 \rangle$  have

cts. partial derivatives on some open region  $R \subseteq \mathbb{R}^2$  and containing a closed region  $D$  w/ piecewise smooth boundary curve.

simple, closed

and ①  $\iint_D \text{curl}(\vec{v}) \cdot \vec{k} \, dA = \oint_{\partial D} \vec{v} \cdot d\vec{r}$

②  $\oint_{\partial D} \vec{v} \cdot (y'(t)\vec{i} - x'(t)\vec{j}) \frac{1}{|r'(t)|} \, ds = \iint_D \text{div}(\vec{v}) \, dA$

Why:

$$\textcircled{1} \text{curl}(\vec{v}) = \langle 0, 0, \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \rangle, \text{ so } \text{curl}(\vec{v}) \cdot \vec{k} = \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}$$

$$\therefore \iint_D \text{curl}(\vec{v}) \cdot \vec{k} \, dA = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

Green's Theorem

$$\begin{aligned} &= \int_a^b P \, dx + Q \, dy \\ &= \int_{t=a}^b (P(x,y) x'(t) + Q(x,y) y'(t)) \, dt \\ &= \int_{t=a}^b \langle P, Q, 0 \rangle \cdot \langle x', y', z' \rangle \, dt \\ &= \int_a^b \vec{v} \cdot d\vec{r} \end{aligned}$$

$$\begin{aligned} \textcircled{2} \iint_D \text{div}(\vec{v}) \, dA &= \iint_D \left( \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} \right) dA \quad \omega = \langle -Q, P, 0 \rangle \\ &= \iint_D \left( \frac{\partial P}{\partial x} - \frac{\partial(-Q)}{\partial y} \right) dA \quad \longleftrightarrow \iint_D \left( \frac{\partial A}{\partial x} - \frac{\partial B}{\partial y} \right) dA \\ &= \int_a^b -Q \, dx + P \, dy \quad \longleftrightarrow \int_a^b A \, dx + B \, dy \\ &= \int_{t=a}^b (-Q x' + P y') \, dt \\ &= \int_{t=a}^b (P y' - Q x') \, dt \\ &= \int_{t=a}^b \langle P, Q \rangle \cdot \langle y', -x' \rangle \, dt \\ &= \int_a^b \vec{v} \cdot (y'(t)\vec{k} - x'(t)\vec{j}) \frac{1}{|\vec{r}'(t)|} \, ds \end{aligned}$$

NB: These two ways of rewriting Green's Theorem with ① curl and ② divergence are jumping points for generalizing Green's theorem

① Generalizing using Curl: Stoke's Theorem

② Generalizing using divergence: Divergence Theorem

Below this line is not on exam 3, but will be on final:

Section 16.6: Parametric Surfaces:

Idea: Generalize space curves to have dimension 2...

Def<sup>n</sup>: A parametric surface in 3-space is given by a vector function:

$\vec{S}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle$  on some domain  $D \subseteq \mathbb{R}^2$ .

Ex: The Euclidean Plane sits in  $\mathbb{R}^3$  as a parametric surface:

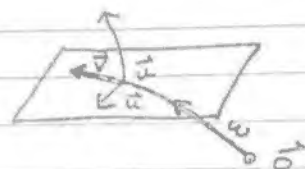
$$\vec{S}(x,y) = \langle x, y, 0 \rangle \text{ on } D = \mathbb{R}^2$$



Ex: Every plane  $\Pi$  in  $\mathbb{R}^3$  can be parameterized in a similar way:

$$\vec{S}(a,b) = a\vec{u} + b\vec{v} + \vec{w} \text{ for suitable } \vec{u}, \vec{v}, \vec{w} \text{ on } D = \mathbb{R}^2$$

I.e.  $\vec{S}(a,b) = \langle u_1 a + v_1 b + w_1, u_2 a + v_2 b + w_2, u_3 a + v_3 b + w_3 \rangle$

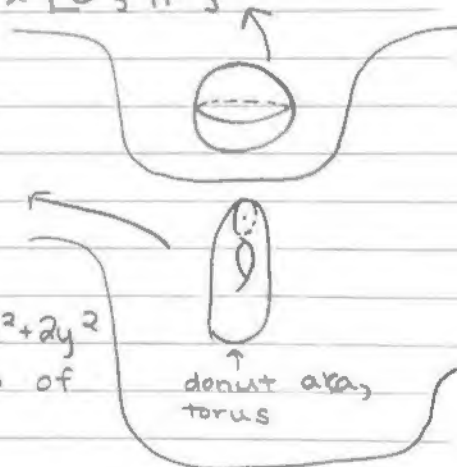


Ex: The sphere of radius  $r > 0$  is parameterized by:

$$\vec{S}(\theta, \varphi) = \langle r \sin(\varphi) \cos(\theta), r \sin(\varphi) \sin(\theta), r \cos(\varphi) \rangle \text{ on } D = [0, 2\pi] \times [0, \pi]$$

Ex: The torus has parameterization

$$\vec{S}(\theta, \varphi) = \langle (2 + \sin(\theta)) \cos(\varphi), (2 + \sin(\theta)) \sin(\varphi), \cos(\theta) \rangle \text{ on } D = [0, 4\pi] \times [0, 2\pi]$$



Ex: Parameterize the paraboloid  $z = x^2 + 2y^2$   
 \* NB: There is no one parameterization of a surface\*

Sol: ①  $\vec{S}(x,y) = \langle x, y, x^2 + 2y^2 \rangle$  on  $D = \mathbb{R}^2$

Sol: ②  $\vec{S}(r, \theta) = \langle r \cos \theta, r \sin \theta, (r \cos \theta)^2 + 2(r \sin \theta)^2 \rangle$   
 $= \langle r \cos \theta, r \sin \theta, r^2 (1 + \sin^2 \theta) \rangle$   
 on  $D = [0, \infty) \times [0, 2\pi]$

Sol: ③  $\vec{S}(r, \theta) = \langle \sqrt{2} r \cos \theta, r \sin \theta, r^2 \rangle$  on  $D = [0, \infty) \times [0, 2\pi]$  □.



Ex: A surface of revolution (about  $x$ -axis)  
be obtained for a function  $f(x)$  via

$$\vec{S}(x, \theta) = \langle x, f(x)\cos\theta, f(x)\sin\theta \rangle \quad f(x) = x+1$$

on  $D = \text{dom}(f) \times [0, 2\pi]$ .  $\forall \theta$ .

